

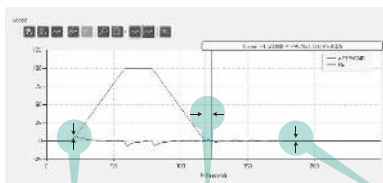
# CDHD2 High-Performance Servo Drives

CDHD2 series features ease of use and advanced control algorithms allowing to build more accurate and more efficient machines.



## HD control loop for optimized servo control

An adaptive non-linear control algorithm was developed to optimize servo performance in high precision motion applications. This proprietary algorithm uses a parallel configuration, in which position and velocity branches are on the same level and executed in each sampling period. A variable gain parameter is introduced and automatically optimized for high gain and stability. As a result, position error and settling time are minimized to levels far superior to those of other controllers.



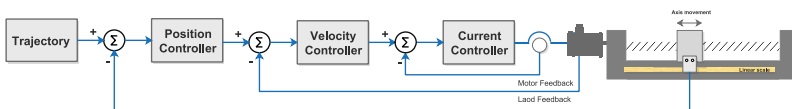
Minimum position error    Settling time of almost zero    No oscillations at stand-still

## High bandwidth current loop achieves and industry-leading frequency response

The current loop design achieves an outstanding frequency response of 3-5 kHz. High sampling rates and flexible filtering options provide a faster response and ensure maximum machine accuracy and throughput.

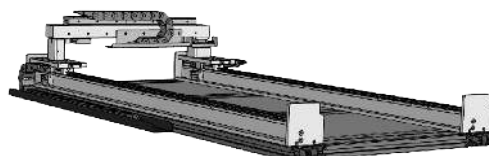
## Dual loop control to eliminate mechanical errors and increase system stability

A dual loop position and velocity controller is used to improve the performance of the complete motion system. CDHD2 supports linear and rotary secondary encoders, both incremental and absolute. The dual loop control is an integral feature of the CDHD2 family and does not require an additional add-on option card.



## Gantry mode

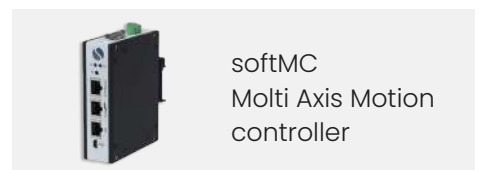
The CDHD2 servo drive has built-in support for both rigid and flexible gantry mechanical systems. The CDHD2 Gantry system synchronizes the two Y axes through two CDHD2 drives working in tandem and using high-speed communication to generate and control movement along the Y axis. Each of the two Y axes can be driven by either a linear or a rotary motor.



## Key benefits

- High performance control of all synchronous servo motors
- Interfaces multiple feedback devices
- Secondary encoder interface for closed dual loop control
- Built in operator panel for drive configuration and diagnostics
- Position compare output module
- Built-in support for both rigid and flexible Gantry
- ID error correction compensation table
- Advanced control algorithms achieve maximum machine accuracy and throughput
- High power density in a small footprint
- Safe Torque Off (STO)
- Simple commissioning with new ServoStudio™ 2.0 GUI along with comprehensive parameterization options for optimal configuration
- 30-month warranty
- Input voltage support: 20 V up to 480 V

## Related products



## ServoStudio™ wizard for simple commissioning

- Step-by-step guidance through the motor setup, application configuration and tuning process
- Innovative and self explanatory user interface
- Excellent results for novice users within minutes
- Real-time data recording and plotting
- Easy integration of servo axes
- Plug-and-play motor library



## Rating and dimensions

Model	Input Voltage	Input Power Main Circuit	Continuous Current (Arms)	Peak Current (Arms)	Width (mm)	Height (mm)	Depth (mm)
CDHD2-003	20-90 VDC	1 phase	3	9	36	167	104
CDHD2-006	20-90 VDC	1 phase	6	18	36	167	104
CDHD2-012	20-90 VDC	1 phase	12	24	36	167	104
CDHD2-015	20-90 VDC	1 phase	15	30	36	167	104
CDHD2-1D5	120/240 VAC	1 phase	1.5	4.5	43.2	150	143.7
CDHD2-003	120/240 VAC	1 phase	3	9	43.2	150	143.7
CDHD2-4D5	120/240 VAC	1/3 phase	4.5	18	54.7	150	167.4
CDHD2-006	120/240 VAC	1/3 phase	6	18	54.7	150	167.4
CDHD2-008	120/240 VAC	1/3 phase	8	28	61.8	170	181.6
CDHD2-010	120/240 VAC	1/3 phase	10	28	61.8	170	181.6
CDHD2-013	120/240 VAC	3 phase	13	28	61.8	170	181.6
CDHD2-020	120/240 VAC	3 phase	20	60	117.4	233.8	193.5
CDHD2-024	120/240 VAC	3 phase	24	72	117.4	233.8	193.5
CDHD2-033	120/240 VAC	3 phase	33	130	157.6	304.3	220.4
CDHD2-044	120/240 VAC	3 phase	44	130	157.6	304.3	220.4
CDHD2-055	120/240 VAC	3 phase	55	130	157.6	304.3	220.4

## Ordering Information

CDHD2 - 006 2A AP1 - RO 000																																																																														
<b>CDHD2 Servo Drive – HD Series</b>																																																																														
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1D	Low Voltage Input Power Supply <ul style="list-style-type: none"> <li>• 20-90 VDC for motor power (for 3A-12A models)</li> <li>• 20-48 VDC for motor power (for 15A model)</li> <li>• 20-48 VDC (optional) for logic power</li> </ul>																																																																													
2A	Medium Voltage Input Power Supply <ul style="list-style-type: none"> <li>• Single Phase 120 L-N VAC +10% -15% 50/60 Hz</li> <li>• Single Phase 240 L-N VAC +10% -15% 50/60 Hz</li> <li>• Three Phase 120-240 L-L VAC +10% -15% 50/60 Hz</li> </ul>																																																																													
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AFx	CANopen, Analog Voltage, Pulse Train, USB, RS232																																																																													
ECx	EtherCAT, Analog Voltage, Pulse Train, USB, RS232																																																																													
EB2	EtherCAT, USB.																																																																													
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[blank]	Rotary and linear servo motors																																																																													
RO	Rotary servo motors. Available in Asia market only.																																																																													
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## Communication:

CANopen®\*  
EtherCAT®\*  
USB\*  
RS232  
Daisy Chain

## Motor feedback:

sensAR Absolute Encoder  
Incremental Encoder  
Hall Sensors  
Resolver\*  
Sine Encoder (e.g., EnDat®, HIPERFACE®)  
SSI Encoder (e.g., EnDat®, Nikon®, Tamagawa®)  
Motor Temperature

## I/Os:\*

Digital: 11 x Input, 6 x Output  
Analog: 1 x Input or 2 x Input\*, 1 x Output  
Pulse & Direction  
Equivalent Encoder Output  
Secondary Feedback  
Fault Output Relay

\*Some features are not available on all models.

